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Research output

A Human-Centered View of Continual Learning: Understanding Interactions, Teaching Patterns, and Perceptions of Human Users Towards a Continual Learning Robot in Repeated Interactions

Ayub, A., De Francesco, Z., Mehta, J., Agha, K. Y., Holthaus, P., Nehaniv, C. L. & Dautenhahn, K., 23 May 2024, (E-pub ahead of print) In: ACM Transactions on Human-Robot Interaction (THRI).

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Human Perception of Intrinsically Motivated Autonomy in Human-Robot Interaction

Scheunemann, M., Salge, C., Polani, D. & Dautenhahn, K., 22 Feb 2022, In: Adaptive Behavior. 32 p.

Use and usability of software verification methods to detect behaviour interference when teaching an assistive home companion robot: A proof-of-concept study

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CORBYS

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Cognitive Robot Companion

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E-Learning Virtual Int. Synth Characters (ELVIS)

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FearNot

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International network joint project (UK and China)

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KASPAR

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KASPAR project for children with autism

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LIREC

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Perception of humanoid robots

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RAAK-Pro

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RoboSkin

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RH2.0: Robot House 2.0

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Robotic visions

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Safety Enables Cooperation in Uncertain Robotic Environments (SECURE)

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1/04/05 → 30/09/05

Social Learning and Artificial Intelligence Symposium

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